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| --- |
| ros2 launch dummy\_robot\_bringup dummy\_robot\_bringup.launch.py  ros2 topic list -t  ros2 msg show std\_msgs/String  ros2 msg show rcl\_interfaces/Log  ros2 msg show unique\_identifier\_msgs/UUID  ros2 topic pub /name unique\_identifier\_msgs/UUID “  > uuid: [1,2,3,4,5,6,7]"  ros2 topic pub /name unique\_identifier\_msgs/UUID "  uuid: [1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16]"  ros2 msg show geometry\_msgs/Twist  ros2 msg show geometry\_msgs/Vector3  ros2 topic pub /name geometry\_msgs/Twist "  {linear:  { x: 1, y: 1, z: 0},  angular:  { x: 4, y: 3, z: 3}  }"  ros2 topic pub /name geometry\_msgs/Twist "  linear:  x: 1  y: 1  z: 3  angular:  x: 3  y: 2  z: 4  " |